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Characterization of an energy dispersive X-ray fluorescence imaging system based on a Micropattern Gaseous Detector

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Abstract

An Energy Dispersive X-ray Fluorescence (EDXRF) imaging system based on a Micropattern Gas Detector has already shown good results for different applications. An X-ray tube, a pinhole camera and a Micro-Hole and Strip Plate (MHSP) based detector are the main components of the experimental system. The detector uses an MHSP in a Xe atmosphere at 1 bar, acting as a photon counting device, i.e., it is capable to record each single event retaining the energy and the interaction position (2D-sensitive detector) information of the incident photon, demonstrating to be a promising device for EDXRF imaging applications. This work presents studies of energy resolution, energy linearity and spatial resolution/elemental mapping as a function of image magnification of the system.

Keywords: Gaseous Detectors, X-ray Fluorescence, Spatial Resolution, Energy Resolution, Energy Linearity

1. Introduction

2 X-ray Fluorescence (XRF) techniques, including analysis and imaging are
3 commonly used in several research fields and industrial applications. Energy
4 Dispersive X-ray Fluorescence (EDXRF) analysis is well-known for elemental
5 identification and quantification, while EDXRF imaging or mapping is a
6 promising method to obtain positional distribution of specific elements in a
7 nondestructive manner. EDXRF imaging can be used in several applications

8 of many different fields such as geology, archaeology, electronics and life
9 sciences [1, 2].

10 To obtain the elemental distribution of a sample it is necessary to use
11 instruments that provide a precise positioning together with a good energy
12 resolution.

13 Following the growing development in the area of gaseous radiation
14 detectors, triggered by the evolving printed circuit technology, new concepts
15 of gaseous radiation detectors emerged in the last years, namely the
16 Micropattern Gaseous Detectors, providing new perspectives for X-ray
17 detection and imaging [3, 4, 5]. Micro-structured charge-amplification devices
18 opened the possibility to apply to gaseous detectors the same technology as
19 used in semiconductor devices. Although the physical operation principle of
20 the gaseous detectors does not allow the excellent energy resolution of the
21 semiconductor detectors, they present important advantages such as: low
22 cost, large detection area and single photon detection [2].

23 One of these structures, the 2D-Micro-Hole and Strip Plate (MHSP)
24 has shown not only fair energy resolution capability of about 825 eV
25 (Full-Width-at-Half-Maximum - FWHM) for 5.9 keV photons but also good
26 spatial resolution of about 130 μm for 8 keV X-ray photons [6]. The
27 Micro-Hole and Strip Plate [7, 8] consists on a double-sided microstructure
28 with a KaptonTM foil of a 50 μm thickness, covered by a thin copper
29 layer on both sides. On the top side, a hole pattern is etched through
30 the microstructure and a pattern of cathode and anode strips is etched
31 on the opposite side (bottom), both patterns are produced through a
32 photolithography process [6]. The holes from the top side pass through the
33 microstructure emerging in the middle of the cathode strips of the bottom
34 side.

35 By applying suitable electric fields inside the holes and between anodes
36 and cathodes, it is possible to induce two independent electron avalanches,
37 achieving high gains: one in the holes and another one near the anode strips.
38 The working principle of the MHSP has been already explained in detail in
39 Refs. [7, 8].

40 For 2D-imaging [6], one of the dimensions is obtained by connecting the
41 anode strips through a thin resistive layer. To obtain the second dimension,
42 the top electrode of the MHSP is structured in strips orthogonal to the
43 previous ones, also interconnected with a resistive line. The charge can be
44 collected from both ends of the orthogonal resistive lines, using the principle
45 of resistive charge division. For each dimension, it is possible to determine

46 the centroid of the electron avalanche distribution, according to the following
47 equation:

$$X = k \frac{X_1 - X_2}{X_1 + X_2} \quad (1)$$

48 where, X is the coordinate of interaction, k is a calibration factor and X_1
49 and X_2 are the amplitudes of the charge signals collected from both sides of
50 the resistive layers. The energy information is obtained from the sum of the
51 two signals collected on the same resistive line:

$$E = k(X_1 + X_2) \quad (2)$$

52 In the present work, we used an acquisition mode with four independent
53 Analog-to-Digital Converters that can be time-correlated, two for each
54 of the two resistive strips. The interaction position of the photons in
55 the microstructure was found by applying equation 1 and the response
56 amplitude/energy by applying equation 2, as already explained in Refs. [2, 6].

57 The aim of this work is to characterize the EDXRF imaging system based
58 on a 2D-MHSP in terms of spatial and energy resolution as well as energy
59 linearity to infer its performance in EDXRF imaging applications.

60 2. The EDXRF imaging system

61 The EDXRF imaging system is composed by an X-ray molybdenum tube
62 (series 5000 Apogee from Oxford), a $200 \pm 8 \mu\text{m}$ tungsten pinhole camera
63 and a 2D-MHSP based detector arranged as shown in Figure 1(a).

64 The detector has an active area of about $28 \times 28 \text{ mm}^2$ and allows to achieve
65 an energy resolution of about 825 eV ($FWHM$) for 5.9 keV X-rays as well
66 as a counting rate of up to 0.5 MHz.

67 For this type of imaging system, it is of major importance to use a device
68 capable to collimate the incoming photons and focus them into the detector.
69 The pinhole collimator, used in this work is, in fact, an aperture through
70 which the photon must pass in order to be detected. It combines the easy
71 manufacturing and production with the possibility of image magnification,
72 which allows, in terms of spatial resolution, overcoming the limits imposed by
73 the intrinsic detector response. The magnification, M , is given by the ratio
74 of the pinhole to detector distance, d , and the pinhole to center of imaged
75 object distance, D , as illustrated in Figure 1(b) [9].

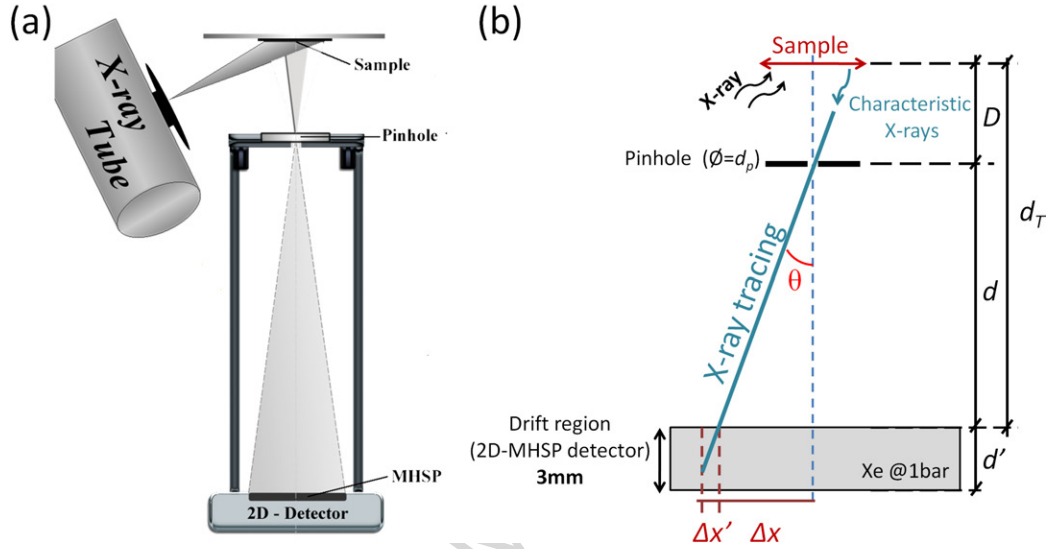


Figure 1: (a) Schematic of the proposed EDXRF imaging system, including an X-ray tube, a pinhole optics and a 2D-MHSP detector [2]. (b) A point source at a distance d_T from the detector emits a photon that passes through the pinhole, located at a distance d from detector. The photon intersects the detector plane with an incident angle θ . $\Delta x'$ is the contribution of oblique penetration of the x-ray photons in the gas medium.

76 In the present case the pinhole is supported by a stainless steel telescopic
 77 tube which allows to change the distance between the pinhole and the
 78 detector thus, varying the magnification of the image obtained [9]. Apart
 79 from this feature, the telescopic tube also avoids the detection of undesirable
 80 X-ray photons [2].

81 The fluorescence process starts when the X-rays, emitted by the X-ray
 82 tube, irradiate the sample and excite the chemical elements present on it.
 83 The characteristic fluorescence X-ray photons emitted by the elements are
 84 focused through the pinhole camera and detected in the gas volume of the
 85 2D-detector. Once the 2D-MHSP detector is able to record both position
 86 and energy information, it is possible to obtain a map of the elements spatial
 87 distribution in the sample, by selecting the X-ray characteristic lines in the
 88 energy spectrum.

89 3. Spatial Resolution vs. Magnification

90 According to Ref. [10] the spatial resolution of a system using pinhole
 91 optics, λ_s , can be determined considering two major contributions: the
 92 intrinsic resolution of the detector, λ_i ; and the contribution of the pinhole, λ_g
 93 which depends on its diameter and on the magnification, M , of the imaging
 94 system:

$$\lambda_s = \sqrt{\lambda_g^2 + \lambda_i^2} = \sqrt{d_p^2 \left(1 + \frac{1}{M}\right)^2 + \frac{FWHM_i^2}{M^2}} \quad (3)$$

95 where, d_p is the aperture diameter of the pinhole and $FWHM_i$ is the intrinsic
 96 position resolution of the detector [10]. The pinhole used in this work has
 97 a thickness of 50 μm . Its transmission is, for a photon energy of 18, 21
 98 and 25 keV, only 4×10^{-4} , 5×10^{-3} and 4×10^{-2} , respectively. From this
 99 expression it is possible to infer the system spatial resolution as a function
 100 of the magnification.

101 In order to experimentally verify that assumption, a study of the spatial
 102 resolution as a function of image magnification was performed. For these
 103 studies, the present system was used, together with a 360 μm stainless steel
 104 hexagonal mesh (sample), shown in Figure 2. The edges of the hexagons had
 105 2.8 mm long. Distances from detector-to-pinhole, d , and pinhole-to-sample,
 106 D , varied in order to get different image magnifications such as: 0.95, 1.25,
 107 1.36, 1.64, 2.00, 2.46, 3.00 and 3.77. The acquisition time for the mesh image
 108 was typically 5 min.

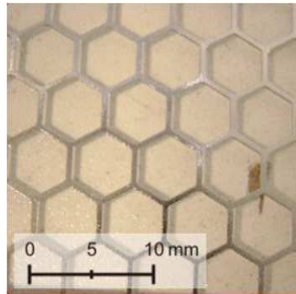


Figure 2: Sample photo: stainless steel hexagonal mesh

109 A summary of the obtained images are presented in Figure 3. From
 110 this figure it is possible to infer that image quality, with respect to spatial
 111 resolution, improves with image magnification.

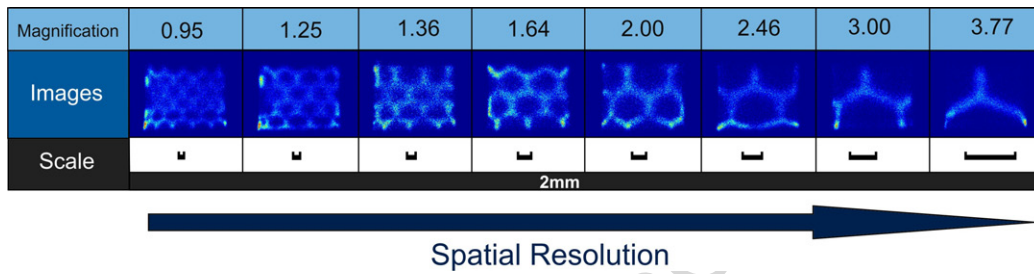


Figure 3: Image results for different magnifications

112 The image of the hexagonal mesh has enough information to allow the
 113 determination of position resolution of the system through the Edge Spread
 114 Function. For this, it is necessary to choose an edge being this enough for
 115 the position resolution determination. For each magnified image, a rectangle
 116 area including a region with and without the mesh edge was selected, as
 117 shown in Figure 4(a)). The obtained Edge Spread Function distribution was
 118 fitted to a sigmoid function (Figure 4(b)). The Full-Width-at-Half-Maximum
 119 of the fitting function (Line Spread Function) is related to the system spatial
 120 resolution [11].

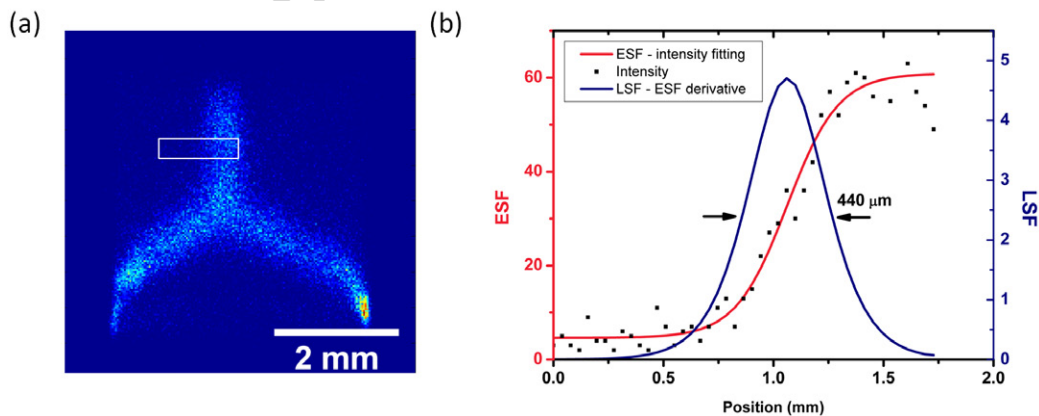


Figure 4: (a) Fluorescence image of the hexagonal mesh with a magnification of 3.77. The selected region for spatial resolution calculations is delimited with a white rectangle. (b) Edge Spread Function (ESF) and Line Spread Function (LSF) used to determine the position resolution.

121 The Modular Transfer Function (MTF) represents the spatial frequency

122 response of an imaging system. This function describes how the imaging
 123 system behaves in the spatial frequency domain, being calculated through
 124 the Fourier transform of the Line Spread Function [11]. In the present work,
 125 we describe the system position resolution using the spatial frequency where
 126 the MTF is reduced to 3%, a value related with the human eye ability to
 127 distinguish low contrast differences in an image [11]. As an example, the MTF
 128 shows a resolution of 2.4 lp/mm (lines-pair per millimeter) at an amplitude
 129 of 3% for the image with higher magnification as illustrated on Figure 5.

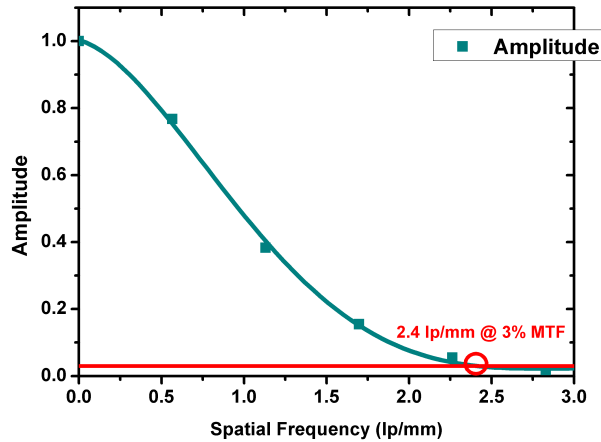


Figure 5: Modulation transfer function (MTF) of the region marked in the image of the Figure 4(a)

130 Figure 6 shows the Modular Transfer Function for all the acquired
 131 magnified images. As can be seen, the spatial frequency increases with the
 132 increase of magnification, meaning that the spatial resolution of the system
 133 is better for higher magnification values, in agreement with equation 3.

134 In Figure 7, the FWHM of the Line Spread Function is presented as a
 135 function of magnification. It is also presented the predicted theoretical curves
 136 from equations 3 and 4.

137 Taking into account the oblique penetration and the different depth of
 138 interaction of X-rays along the detector drift region (illustrated in Figure
 139 1(b)), an uncertainty $\Delta x'$ needs to be added as a contribution to equation 3,
 140 which is represented by the third term of the following equation:

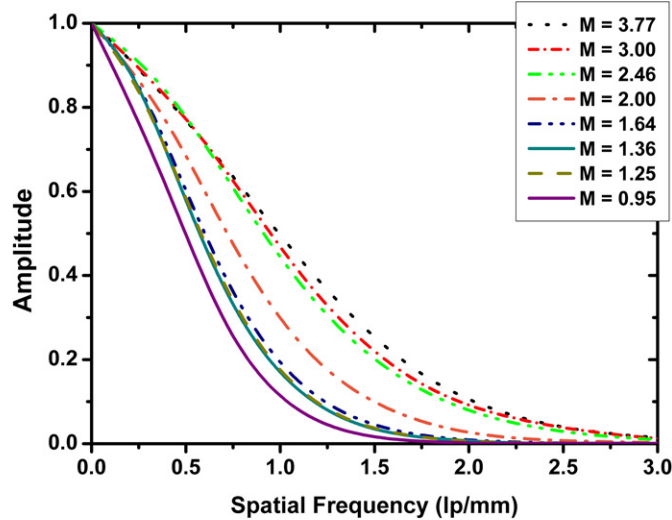


Figure 6: Modular transfer function for the images obtained for different magnifications

$$\begin{aligned} \lambda_s &= \sqrt{\lambda_g^2 + \lambda_i^2 + \lambda_{\Delta x'}^2} \\ \Leftrightarrow \lambda_s &= \sqrt{d_p^2 \left(1 + \frac{1}{M}\right)^2 + \frac{FWHM_i^2}{M^2} + \frac{(d' \Delta x / d_T)^2}{M^2} \left(1 + \frac{1}{M}\right)^2} \quad (4) \end{aligned}$$

141 Thus, the equation 4 takes into account not only with the contribution
 142 of the intrinsic resolution of the detector, λ_i , and with the contribution of
 143 the pinhole, λ_g , but also with the contribution of the oblique penetration of
 144 the X-rays along the detector drift region, $\lambda_{\Delta x'}$. This dependence (Eqn. 4)
 145 is plotted in Figure 7. This plot shows that the contribution of the X-ray
 146 photons oblique penetration is small and can be considered negligible for
 147 highest magnification values. The calculations for this contribution were
 148 made to a value of Δx close to window limits which means that the curve
 149 obtained corresponds to the worst possible situation. The experimental
 150 system spatial resolution ($FWHM$) varies between 900 and 400 μm for
 151 an image magnification between about 1 and 4. Both, experimental and
 152 theoretical predictions present the same trend and experimental curves
 153 approaches the theoretical one for higher values of M . Nevertheless, position

154 resolutions obtained for the experimental data are little worse than the
 155 theoretical values, possibly due to some non-uniformities of the sample, the
 156 pinhole, and the detector.

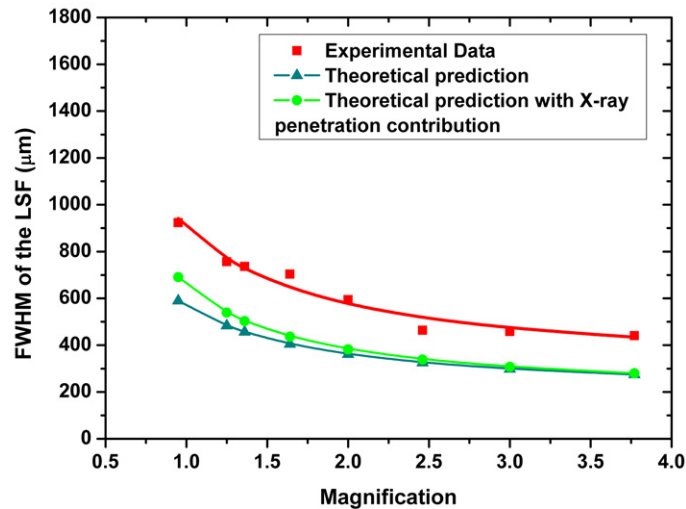


Figure 7: *FWHM* of the Line Spread Function as a function of magnification: comparison between experimental and theoretical predictions

157 According to equation 3 and 4, the intrinsic resolution of the detector is
 158 more significant for lower values of magnification.

159 Note also that the spatial resolution saturates to a value close to pinhole
 160 diameter (Figure 7). This means that the pinhole diameter limits the spatial
 161 resolution of the system, even if we further increase the image magnification
 162 or/and the detector position resolution. To reach higher spatial resolutions,
 163 it is mandatory to use a pinhole with a smaller aperture. By reducing
 164 the pinhole diameter it is possible to further improve the system imaging
 165 resolution, however it will produce a quadratic reduction of the pinhole
 166 efficiency [10]. Thus, it is necessary to establish a compromise between the
 167 spatial resolution and the detection efficiency of the system.

168 **4. Energy linearity and Energy Resolution**

169 The energy linearity of the EDXRF system was determined for X-ray
 170 photons within an energy range between 3 and 25 keV. Fluorescence radiation
 171 was obtained by irradiation of different single-element targets including pure
 172 elements, oxides or salts, such as: Ca, V, Cr, Mn, Fe, Co, Ni, Cu, Zn, Ge,
 173 Zr, Mo, Pd e Sn. The time of acquisition was typically 30s. As an example,
 174 the Cu and Mo K-lines spectra can be seen on Figure 8.

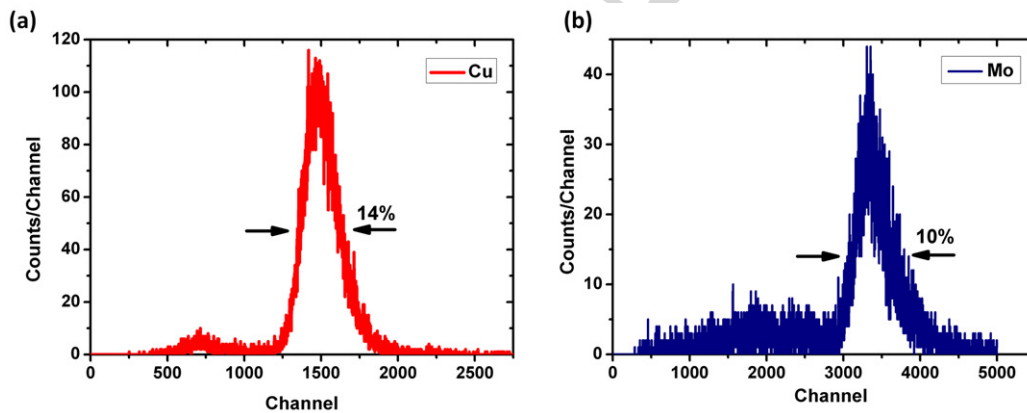


Figure 8: Pulse height distributions of K-lines from: (a) Cu and; (b) Mo

175 During acquisitions, the sample-to-detector distance was typically 20 cm.
 176 The detector window was coupled to a lead collimator containing a hole
 177 with 2 mm diameter. Fluorescence radiation was induced by X-rays from
 178 the X-ray tube by using different currents and voltages depending on the
 179 analyzed sample.

180 In Figure 9(a) the pulse amplitude (the centroid of the peak distribution)
 181 and the energy resolution values of the measured pulse-height distributions
 182 are plotted as a function of X-ray energy. As expected, good energy linearity
 183 is maintained throughout the measured energy range. The energy resolution
 184 shows also a reasonable linearity with $E^{-1/2}$, as illustrated in Figure 9(b).

185 Although energy resolution behaves as expected, the obtained values
 186 are still worse than the intrinsic energy resolution of the detector. It is
 187 known that the amplitude response as a function of interaction position in
 188 the detector is not a constant value for monochromatic radiation photons.
 189 This is due to the different response along the microstructure because of

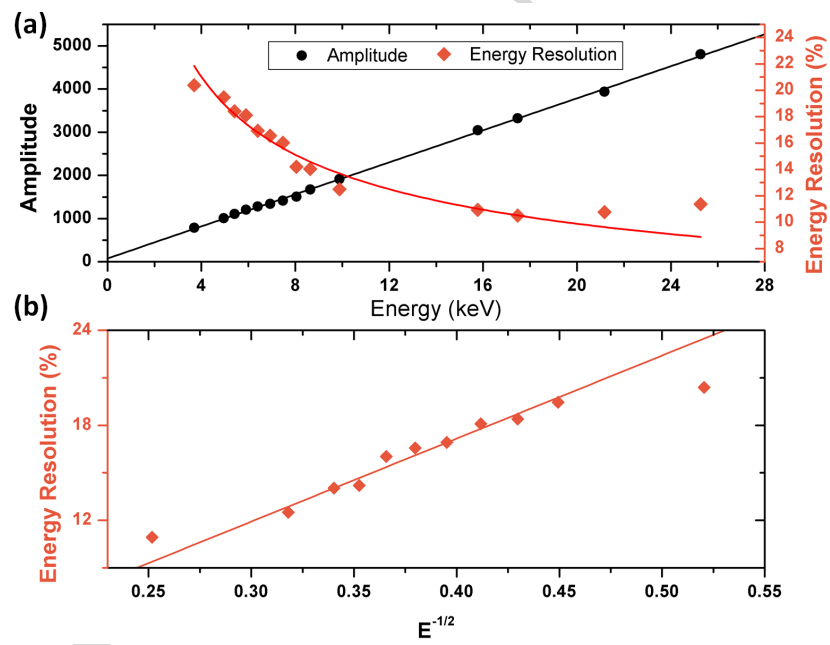


Figure 9: (a) Pulse amplitude and energy resolution as a function of X-ray energy; (b) Energy resolution as a function of the inverse of square root of the X-ray energy.

190 the non-uniformities resulting from the fabrication process and leads to a
 191 deterioration of energy resolution. To overcome this problem an amplitude
 192 correction method was developed, which was explained in detail in Ref. [2].

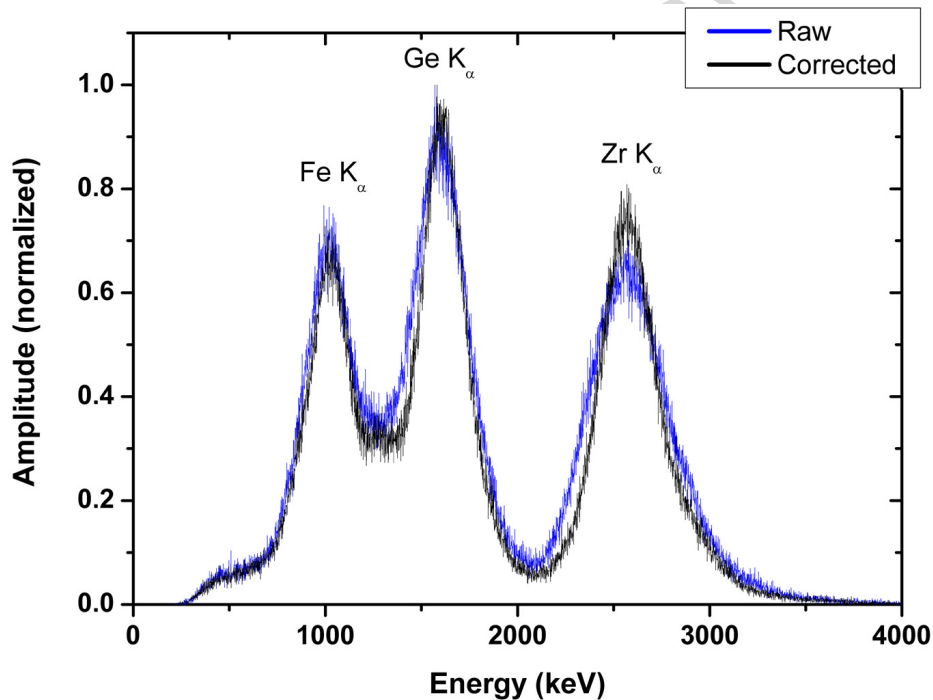


Figure 10: Raw and corrected pulse height distributions from a Fe, Ge and Zr sample

193 As can be seen in Figure 10, the correction method gives a clear
 194 improvement in the energy resolution and on the shape of fluorescence
 195 spectrum of the three-element sample example. For an energy of 9.89
 196 and 15.77 keV, an improvement in the energy resolution of 17% and 24%,
 197 respectively, was obtained in comparison with the non-corrected one. This
 198 spectrum was obtained irradiating the whole active area of the detector.

199 A spectrum was also acquired by direct irradiation of the detector with
 200 an ^{241}Am γ source to evaluate the detector energy dynamic range, Figure
 201 11. The spectral features include the fluorescence L-lines from Neptunium
 202 (respectively 13.95, 17.74 and 20.78 keV), the 59.6 keV peak from ^{241}Am
 203 γ -rays and other fluorescence lines associated with the experimental setup
 204 (Pb from the collimator and Xe escape lines). The spectrum shows clearly

205 the detector intrinsic high energy dynamic range.

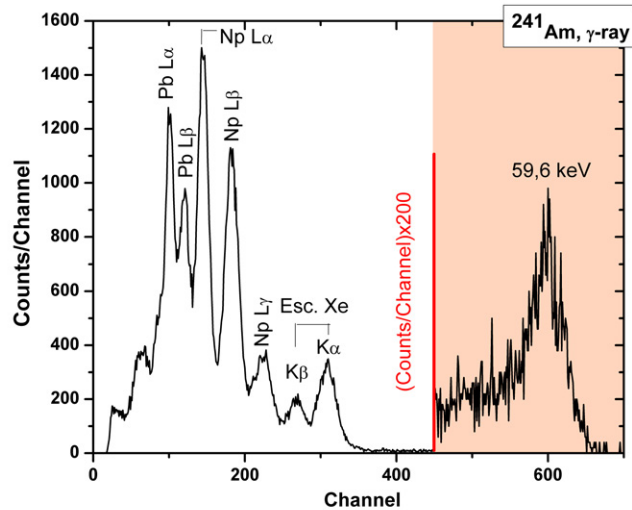


Figure 11: ^{241}Am pulse-height distribution

206 5. Conclusions

207 The performance characteristics of the energy dispersive X-ray
 208 fluorescence imaging system based on a 2D-MHSP detector, filled with Xe
 209 at 1 bar, have been presented.

210 The spatial resolution of the system was determined as a function of
 211 image magnification due to the use of pinhole optics. As expected the
 212 increase of image magnification improves the spatial resolution. Spatial
 213 resolution ($FWHM$) of the experimental system varied between 900 and 400
 214 μm for image magnifications between 1 and 4. The contribution of oblique
 215 penetration of X-ray photons was found to be negligible for high values of
 216 magnification. Future work will include the increase of the spatial resolution
 217 by using a pinhole with a smaller aperture.

218 Energy resolution and linearity, in the 3-25 keV X-ray energy range were
 219 determined from the pulse-height distributions of the fluorescence X-ray
 220 spectra induced in a variety of single- and multi-element sample materials.

221 The energy resolution have shown good linearity with the inverse of the
222 square root of the X-ray energy.

223 Future development work will focus also on the improvement of the gas
224 purification in order to further improve the energy resolution, by using getters
225 coupled to the detector; and on the improvement of the detection efficiency
226 by increasing the drift region and/or the gas pressure; as well as the increase
227 of the effective area of the detector.

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