

# HOMOGENIZATION OF OBSTACLE PROBLEMS IN ORLICZ-SOBOLEV SPACES

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**ABSTRACT.** We study the homogenization of obstacle problems in Orlicz-Sobolev spaces for a wide class of monotone operators (possibly degenerate or singular) of the  $p(\cdot)$ -Laplacian type. Our approach is based on the Lewy-Stampacchia inequalities, which then give access to a compactness argument. We also prove the convergence of the coincidence sets under non-degeneracy conditions.

**Keywords:** Homogenization, obstacle problem, Orlicz-Sobolev spaces, convergence of coincidence sets.

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## 1. INTRODUCTION

Let  $\Omega \subset \mathbb{R}^n$  be a bounded domain and  $p : \Omega \rightarrow \mathbb{R}$  be measurable and such that

$$1 < \alpha \leq p(x) \leq \beta < \infty \quad \text{a.e. in } \Omega, \quad (1.1)$$

where  $\alpha$  and  $\beta$  are constants. The following variable exponent Lebesgue space is an Orlicz space:

$$L^{p(\cdot)}(\Omega) := \left\{ u : \Omega \rightarrow \mathbb{R} \text{ measurable } \rho(u) := \int_{\Omega} |u(x)|^{p(x)} dx < \infty \right\}.$$

This Orlicz space is a separable reflexive Banach space with the following (Luxembourg) norm:

$$\|u\|_{L^{p(\cdot)}(\Omega)} := \inf \left\{ \lambda > 0, \rho\left(\frac{|u|}{\lambda}\right) \leq 1 \right\}.$$

We define an Orlicz-Sobolev space by

$$W^{1,p(\cdot)}(\Omega) := \left\{ u \in L^{p(\cdot)}(\Omega), \nabla u \in \left( L^{p(\cdot)}(\Omega) \right)^n \right\},$$

with the norm

$$\|u\|_{W^{1,p(\cdot)}(\Omega)} := \|u\|_{L^{p(\cdot)}(\Omega)} + \|\nabla u\|_{L^{p(\cdot)}(\Omega)}, \quad \|\nabla u\|_{L^{p(\cdot)}(\Omega)} = \sum_{i=1}^n \left\| \frac{\partial u}{\partial x_i} \right\|_{L^{p(\cdot)}(\Omega)}.$$

This Orlicz-Sobolev space is also a separable and reflexive Banach space. We also define

$$W_0^{1,p(\cdot)}(\Omega) := \left\{ u \in W_0^{1,1}(\Omega), \rho(|\nabla u|) < \infty \right\}.$$

The latter is a Banach space endowed with the norm

$$\|u\|_{W_0^{1,p(\cdot)}(\Omega)} := \|\nabla u\|_{L^{p(\cdot)}(\Omega)}.$$

In this paper we study the periodic homogenization of obstacle problems in Orlicz-Sobolev spaces. We consider

$$a(x, \xi) : \Omega \times \mathbb{R}^n \rightarrow \mathbb{R}^n$$

to be a Carathéodory vector function, that is, we assume it is continuous with respect to  $\xi$ , for almost every  $x \in \mathbb{R}^n$ , and that it is measurable with respect to  $x$ , for every  $\xi$ . Moreover, the functions  $a(\cdot, \xi)$  and  $p(\cdot)$  are assumed to be periodic with period 1 in each argument  $x_1, x_2, \dots, x_n$ . We denote the periodicity cell by  $Q$ , i.e.  $Q := (0, 1]^n$ . Additionally, we assume that the following structural conditions (monotonicity, coercitivity and boundedness) hold:

$$\begin{cases} (a(x, \xi) - a(x, \eta)) \cdot (\xi - \eta) > 0, & \text{for a.e. } x, \xi \neq \eta, \\ a(x, \xi) \cdot \xi \geq C_1 (|\xi|^{p(x)} - 1), \\ |a(x, \xi)| \leq C_2 (|\xi|^{p(x)-1} + 1), \end{cases} \quad (1.2)$$

where  $C_1, C_2 > 0$  are constants. For  $\varepsilon > 0$ , we define

$$a_\varepsilon(x, \xi) := a\left(\frac{x}{\varepsilon}, \xi\right), \quad x \in \Omega, \xi \in \mathbb{R}^n \quad (1.3)$$

and  $p_\varepsilon(x) = p(x/\varepsilon)$ . The Orlicz-Sobolev spaces of periodic functions, denoted by  $W_{\text{per}}^{1,p(\cdot)}(Q)$ , is defined as the set of periodic functions  $u$  from  $W_{\text{per}}^{1,1}(Q)$  with

$$\int_Q u \, dx = 0 \quad \text{and} \quad \int_Q |\nabla u|^{p(x)} \, dx < \infty.$$

For the homogenized functional defined by

$$h(\xi) := \min_{v \in W_{\text{per}}^{1,p(\cdot)}(Q)} \int_Q \frac{|\xi + \nabla v|^{p(x)}}{p(x)} \, dx, \quad (1.4)$$

we introduce also the Orlicz-Sobolev spaces

$$W^h(\Omega) := \left\{ u \in W^{1,1}(\Omega), h(\nabla u) \in L^1(\Omega) \right\},$$

$$W_0^h(\Omega) := \left\{ u \in W_0^{1,1}(\Omega), h(\nabla u) \in L^1(\Omega) \right\},$$

with the norm,  $\|u\|_{W_0^h(\Omega)} := \|\nabla u\|_{L^h(\Omega)}$ , and the vector Orlicz space

$$L^h(\Omega) := \left\{ \xi \in [L^1(\Omega)]^n, h(\xi) \in L^1(\Omega) \right\},$$

normed by

$$\|\xi\|_{L^h(\Omega)} := \inf \left\{ \lambda > 0, \int_\Omega h\left(\frac{\xi}{\lambda}\right) \leq 1 \right\}.$$

By the properties of  $h$ , as it was observed in [24], we have the continuous embeddings

$$L^\beta(\Omega) \subset L^h(\Omega) \subset L^\alpha(\Omega),$$

Assuming that

$$f \text{ and } (A_\varepsilon \psi_\varepsilon - f)^+ \in L^s(\Omega), \quad (1.5)$$

$$\|(A_\varepsilon \psi_\varepsilon - f)^+\|_{L^s(\Omega)} \leq C, \quad (1.6)$$

where  $C > 0$  is a constant independent of  $\varepsilon$  and

$$\psi_\varepsilon \in W^{1,p_\varepsilon(\cdot)}(\Omega), \quad \psi_0 \in W^h(\Omega), \quad \psi_\varepsilon^+ \in W_0^{1,p_\varepsilon(\cdot)}(\Omega), \quad \psi_0^+ \in W_0^h(\Omega), \quad (1.7)$$

where  $\alpha' = \alpha/(\alpha - 1)$ ,  $u^+$  is the positive part of  $u$  and  $s > \frac{n\alpha'}{n+\alpha'}$  if  $\alpha < n$ ,  $s > 1$ , if  $\alpha = n$  and  $s = 1$  for  $\alpha > n$ , we show (Theorem 3.1) that the unique solution  $u_\varepsilon \in K_\varepsilon$  of the obstacle problem

$$\int_{\Omega} a_\varepsilon(x, \nabla u_\varepsilon) \cdot \nabla(v - u_\varepsilon) dx \geq \int_{\Omega} f(v - u_\varepsilon) dx, \quad \forall v \in K_\varepsilon, \quad (1.8)$$

where

$$K_\varepsilon := \left\{ v \in W_0^{1,p_\varepsilon(\cdot)}(\Omega), v \geq \psi_\varepsilon \text{ a.e. in } \Omega \right\},$$

converges to the unique solution  $u_0 \in K_0$  of the following homogenized obstacle problem

$$\int_{\Omega} a_0(\nabla u_0) \cdot \nabla(v - u_0) dx \geq \int_{\Omega} f(v - u_0) dx, \quad \forall v \in K_0, \quad (1.9)$$

where

$$K_0 := \left\{ v \in W_0^h(\Omega), v \geq \psi_0 \text{ a.e. in } \Omega \right\}.$$

The homogenized operator  $a_0 : \mathbb{R}^n \rightarrow \mathbb{R}^n$  is given in terms of the weighted average of  $a$  as in [24], that is,

$$a_0(\xi) := \int_Q a(x, \xi + \nabla v) dx, \quad (1.10)$$

with  $v \in W_{\text{per}}^{1,p(\cdot)}(Q)$ , such that,

$$\int_Q a(x, \xi + \nabla v) \cdot \nabla \varphi dx = 0, \quad \forall \varphi \in W_{\text{per}}^{1,p(\cdot)}(Q),$$

where  $Q$  is the periodicity cell.

Note that, due to the Lavrent'ev effect, if instead of  $W_{\text{per}}^{1,p(\cdot)}(Q)$ , we take  $\varphi \in C_{\text{per}}^\infty(Q)$ , we may end up with a different homogenized operator, since in general the space  $C_{\text{per}}^\infty(Q)$  is not dense in  $W_{\text{per}}^{1,p(\cdot)}(Q)$ . These homogenized operators, referred to as  $W$  and  $H$  solutions in [24], respectively, in general may be different, but our results hold for both solutions, with minor modifications for the space framework of the  $H$  solutions. Although we prefer to work with  $W$  solutions, that is due to the fact that [24, Theorem 3.1] (see Theorem 2.1 below) is true for both types of solutions. Observe that we do

not impose any regularity assumption on  $p(\cdot)$ . However, in the particular case when  $p$  is log-Lipschitz continuous, i.e., when for a constant  $L > 0$

$$-|p(x) - p(y)| \log |x - y| \leq L, \quad \forall x, y \in \overline{\Omega}, \quad |x - y| < 1/2,$$

the notion of  $W$  and  $H$  solutions coincide (see [10, 14]), since then the smooth functions are dense in the Orlicz-Sobolev space.

Our approach is a development of the classical methods [6, 11] (see also [20, 21, 24]) combined with the Lewy-Stampacchia inequalities in the Orlicz-Sobolev framework, in accordance with [19], which then allows the use of a Rellich-Kondrachov compactness argument.

The result generalizes, in part, that of [5], which covers the case when  $p$  is constant (and hence the homogenization is in usual Sobolev spaces). The latter, in turn, implies the case of  $p = 2$  obtained in [4]. Nonetheless, we observe that the structural assumptions (1.2) allow us to consider a wider range of monotone operators, which cover these cases and include other interesting quasilinear operators, some of which we list below.

1. If  $a(x, \xi) = |\xi|^{p(x)-2}\xi$ , we deal with the obstacle problem for the  $p(x)$ -Laplace operator.
2. We can also consider perturbations of the  $p$ -Laplace ( $p$  constant) and of the  $p(x)$ -Laplace operators, taking

$$a(x, \xi) = \gamma(x)|\xi|^{p-2}\xi \quad \text{and} \quad a(x, \xi) = \gamma(x)|\xi|^{p(x)-2}\xi$$

for any non-negative bounded periodic function  $\gamma(x)$ .

3. It is possible to consider functions which are essentially different from these previous “power like” functions. One general example can be

$$a(x, \xi) = \gamma_1(x)|\xi|^{p(x)-1}\xi \log(\gamma_2(x)|\xi| + \gamma_3(x)),$$

where  $\gamma_3(x)$ ,  $p(x) > 1$  and  $\gamma_1(x)$ ,  $\gamma_2(x) > 0$  a.e. in  $\Omega$  are bounded periodic functions.

The paper is organized as follows: in Section 2, we state some preliminaries facts, which then serve to prove our main result in Section 3 (Theorem 3.1). In Section 4, we prove the convergence of the coincidence sets (Theorems 4.1 and 4.2).

## 2. PRELIMINARIES

In this section we give some preliminaries. In particular, we provide the concept of  $G$ -convergence of operators in our framework, as well as convergence of sets in Mosco sense. We also recall some results from [22] and [24] for future reference. We start by setting some notations, which will be used throughout the paper:  $p_\varepsilon(x) = p(x/\varepsilon)$ ;  $\alpha' = \frac{\alpha}{\alpha-1}$ ;  $\rightharpoonup$  denotes the weak convergence;

$$A_\varepsilon u := -\operatorname{div}(a_\varepsilon(x, \nabla u)) \quad \text{and} \quad A_0 u := -\operatorname{div}(a_0(\nabla u)),$$

where  $a_\varepsilon$  is defined by (1.3), and  $a_0$  is defined by (1.10). Next, we define the notion of  $G$ -convergence of  $a_\varepsilon$  to  $a_0$ . Observe, that most definitions of  $G$ -convergence that can be found in the literature (see, for example, [2, 3, 7, 17]), allow  $a_0$  to depend on  $x$  as well, just as  $a_\varepsilon$  depends. However, in some particular cases, more information can be said about the limiting operator. One example is that of operators with rapidly oscillating ‘‘coefficients’’. Since our assumptions ensure that  $a(x, \xi)$  and  $p(\cdot)$  are periodic with respect to  $x$  in each of the arguments  $x_1, x_2, \dots, x_n$ , there is no loss in generality to impose  $a_0$  to be independent of  $x$  in the definition of  $G$ -convergence, which is more relevant for our purposes.

**Definition 2.1.** *Consider  $a_\varepsilon : \Omega \times \mathbb{R}^n \rightarrow \mathbb{R}^n$  and  $a_0 : \mathbb{R}^n \rightarrow \mathbb{R}^n$  as above. We say that  $a_\varepsilon$   $G$ -converges to  $a_0$  when, considering the unique solution  $u_\varepsilon \in W_0^{1,p_\varepsilon(\cdot)}(\Omega)$  of*

$$-\operatorname{div}(a_\varepsilon(x, \nabla u_\varepsilon)) = f, \quad f \in W_0^{-1,\alpha'}(\Omega) \text{ in } \mathcal{D}'(\Omega)$$

and  $u_0 \in W_0^h(\Omega)$  the unique solution of

$$-\operatorname{div}(a_0(\nabla u_0)) = f \text{ in } \mathcal{D}'(\Omega),$$

there holds:

- (1)  $u_\varepsilon \rightharpoonup u_0$  in  $W_0^{1,\alpha}(\Omega)$ , as  $\varepsilon \rightarrow 0$ ;
- (2)  $a_\varepsilon(x, \nabla u_\varepsilon) \rightharpoonup a_0(\nabla u_0)$  in  $(L^{\beta'}(\Omega))^n$ , as  $\varepsilon \rightarrow 0$ .

Note that the choice of  $s$  in (1.5) guarantees, in particular,  $f \in W^{-1,\alpha'}(\Omega)$ . Additionally,  $a(x, \xi)$  is assumed to be continuous with respect to  $\xi$ , for almost every  $x \in \mathbb{R}^n$ .

Next, we state a theorem from [24, Theorem 3.1] that insures the  $G$ -convergence of  $a_\varepsilon$  to a function  $a_0$ , as  $\varepsilon \rightarrow 0$ , given explicitly in terms of  $a$ . Its proof is based on a compensated compactness argument from [23, 24], which, in the case of  $p(\cdot) = \text{constant}$ , resembles the well known result of Tartar-Murat (see [16]).

**Theorem 2.1.** *Let  $a(x, \xi)$  be a Carathéodory vector function, which is periodic with respect to  $x$  in each argument and satisfy (1.2). Let also  $p$  be periodic, measurable and satisfy (1.1). If structural conditions (1.2) hold, then  $a_\varepsilon$   $G$ -converges to  $a_0$ , where  $a_0$  is defined by (1.10). Moreover,*

$$\int_{\Omega} a_\varepsilon(x, \nabla u_\varepsilon) \cdot \nabla u_\varepsilon \, dx \rightarrow \int_{\Omega} a_0(\nabla u_0) \cdot \nabla u_0 \, dx,$$

as  $\varepsilon \rightarrow 0$ .

As it is shown in [24], the vector function  $a_0(\xi)$  is strictly monotone, i.e.,

$$(a_0(\xi) - a_0(\eta)) \cdot (\xi - \eta) > 0, \quad \xi \neq \eta,$$

and coercive, that is,

$$a_0(\xi) \cdot \xi > c_0(h(\xi) - 1),$$

where  $c_0 > 0$  is a constant, and the homogenized functional  $h(\xi)$  is defined by (1.4). Moreover,  $h$  satisfies the so-called  $\Delta_2$  condition, [24, Proposition 2.1], which implies that the Orlicz space  $L^h(\Omega)$  is reflexive. As it is observed in [24],  $h(\xi)$  being defined by (1.4), is convex on  $\mathbb{R}^n$  and satisfies the following two-sided estimate:

$$c_1|\xi|^\alpha - 1 \leq h(\xi) \leq c_2|\xi|^\beta + 1,$$

for a  $c_1 > 0$  constant. As a consequence, we have

$$W_0^{1,\beta}(\Omega) \subset W_0^h(\Omega) \subset W_0^{1,\alpha}(\Omega),$$

which implies that

$$K_0 \subset W_0^{1,\alpha}(\Omega).$$

The following result is from [22], and it provides more information on the homogenized functional.

**Lemma 2.1.** *If  $u_\varepsilon$  is a sequence uniformly bounded in  $W_0^{1,p_\varepsilon(\cdot)}(\Omega)$ , such that,  $u_\varepsilon \rightharpoonup u_0$  in  $W_0^{1,\alpha}(\Omega)$  as  $\varepsilon \rightarrow 0$ , then  $h(\nabla u_0) \in L^1(\Omega)$ .*

Observe that Lemma 2.1 guarantees that, within  $G$ -convergence, the weak limits of  $u_\varepsilon$  in  $W_0^{1,\alpha}(\Omega)$  belong to  $W_0^h(\Omega)$ , and therefore, if also  $u_\varepsilon \in K_\varepsilon$  then  $u_0 \in K_0$ .

In order to state our main result, we will also need to redefine the Mosco convergence of sets.

**Definition 2.2.** *The sequence of closed convex sets  $K_\varepsilon \subset W_0^{1,p_\varepsilon(\cdot)}(\Omega)$ , is said to converge to the set  $K_0 \subset W_0^h(\Omega)$  in the Mosco sense, if*

- for any  $v_0 \in K_0$  there exists a sequence  $v_\varepsilon \in K_\varepsilon$ , such that,  $v_\varepsilon \rightarrow v_0$  in  $W_0^{1,\alpha}(\Omega)$ ;
- weak limits in  $W_0^{1,\alpha}(\Omega)$  of any sequence of elements in  $K_\varepsilon$ , that is uniformly bounded in  $W_0^{1,p_\varepsilon(\cdot)}(\Omega)$ , belong to  $K_0$ .

**Remark 2.1.** *Since  $W_0^{1,p_\varepsilon(\cdot)}(\Omega)$  is continuously embedded into  $W_0^{1,\alpha}(\Omega)$  (see, for example, [10]), then  $\psi_\varepsilon \rightarrow \psi_0$  in  $W^{1,\beta}(\Omega)$  provides  $K_\varepsilon \rightarrow K_0$  in the Mosco sense, where  $K_\varepsilon$  and  $K_0$  are as in (1.8) and (1.9) respectively.*

### 3. HOMOGENIZATION OF THE OBSTACLE PROBLEM

We are now ready to prove our main result, which states as follows.

**Theorem 3.1.** *Let  $a(x, \xi)$  be a Carathéodory vector function satisfying (1.2) and periodic with respect to  $x$  in each argument. Let  $p(\cdot)$  be periodic, measurable and satisfying (1.1). Assume further that (1.5)-(1.7) hold. If  $K_\varepsilon \rightarrow K_0$  in the Mosco sense, then the unique solution of (1.8) converges weakly in  $W_0^{1,\alpha}(\Omega)$ , as  $\varepsilon \rightarrow 0$ , to the unique solution of (1.9), where  $a_0$  is given by (1.10).*

*Proof.* We divide the proof into five steps.

**Step 1** (*A priori estimates*). Existence and uniqueness of the solution of (1.8) (and (1.9)) is a classical result (see, for instance, [9, 18, 19]). As in the proof of [5, Theorem 2.3] (see also [18, page 145]), the coercitivity and boundedness assumptions from (1.2) imply that  $u_\varepsilon$  is bounded in  $W_0^{1,p_\varepsilon(\cdot)}(\Omega)$  by a constant depending only from  $C_1, C_2$  but independent of  $\varepsilon$ . For the details we refer the reader to [12]. As a consequence we obtain that  $u_\varepsilon$  is bounded also in  $W_0^{1,\alpha}(\Omega)$ , since  $W_0^{1,p_\varepsilon(\cdot)}(\Omega) \subset W_0^{1,\alpha}(\Omega)$ . Set

$$\sigma_\varepsilon := a_\varepsilon(x, \nabla u_\varepsilon), \quad \mu_\varepsilon := -\operatorname{div}(a_\varepsilon(x, \nabla u_\varepsilon)) - f. \quad (3.1)$$

The boundedness condition from (1.2) implies that  $\sigma_\varepsilon$  and  $\mu_\varepsilon$  are bounded (see [5, 24]), therefore we can extract weakly convergent subsequence (still denoted by  $\varepsilon$ ) from each one of them. Thus, there exist  $u^*, \sigma^*, \mu^*$  such that

$$u_\varepsilon \rightharpoonup u^* \quad \text{in } W_0^{1,\alpha}(\Omega) \quad \text{and} \quad u_\varepsilon \rightarrow u^* \quad \text{in } L^\alpha(\Omega), \quad (3.2)$$

$$\sigma_\varepsilon \rightharpoonup \sigma^* \quad \text{in } \left(L^{\beta'}(\Omega)\right)^n, \quad (3.3)$$

$$\mu_\varepsilon \rightharpoonup \mu^* \quad \text{in } W^{-1,\beta'}(\Omega). \quad (3.4)$$

Note that

$$\mu^* = -\operatorname{div}\sigma^* - f. \quad (3.5)$$

Moreover, using Lemma 2.1 and since  $K_\varepsilon \rightarrow K_0$  in the Mosco sense, then

$$u^* \in K_0. \quad (3.6)$$

**Step 2** (*Compactness*). Note that our assumptions provide the Lewy-Stampacchia inequalities (see [19]), that is, we have

$$f \leq f + \mu_\varepsilon \leq (A_\varepsilon \psi_\varepsilon - f)^+ + f,$$

which implies, by a Rellich-Kondrachov compactness argument,

$$\mu_\varepsilon \rightarrow \mu^* \quad \text{in } W^{-1,\alpha'}(\Omega). \quad (3.7)$$

**Step 3.** In this step we prove that  $\sigma^* = a_0(\nabla u^*)$ , where  $a_0$  is defined by (1.10). To see this, let  $w_0 \in \mathcal{D}(\Omega)$  and  $w_\varepsilon \in W_0^{1,p_\varepsilon(\cdot)}(\Omega)$  be the unique solution of

$$\operatorname{div}(a_\varepsilon(x, \nabla w_\varepsilon)) = \operatorname{div}(a_0(\nabla w_0)) \quad \text{in } \mathcal{D}'(\Omega). \quad (3.8)$$

From Theorem 2.1, we have that  $a_\varepsilon$   $G$ -converges to  $a_0$ , as  $\varepsilon \rightarrow 0$ , where  $a_0(\xi)$  is defined by (1.10). In particular,

$$\begin{cases} w_\varepsilon \rightharpoonup w_0 & \text{in } W^{1,\alpha}(\Omega) \\ a_\varepsilon(x, \nabla w_\varepsilon) \rightharpoonup a_0(\nabla w_0) & \text{in } \left(L^{\beta'}(\Omega)\right)^n. \end{cases} \quad (3.9)$$

Fix now  $\varphi$  such that

$$\varphi \in \mathcal{D}(\Omega), \quad 0 \leq \varphi \leq 1. \quad (3.10)$$

From the monotonicity of  $a_\varepsilon$  one has

$$\int_{\Omega} \varphi (a_\varepsilon(x, \nabla u_\varepsilon) - a_\varepsilon(x, \nabla w_\varepsilon)) \cdot (\nabla u_\varepsilon - \nabla w_\varepsilon) dx \geq 0. \quad (3.11)$$

Since  $u^* \in K_0$ , and  $K_\varepsilon \rightarrow K_0$  in the Mosco sense, there exists a sequence  $\bar{u}_\varepsilon$ , such that,

$$\bar{u}_\varepsilon \in K_\varepsilon \quad \text{and} \quad \bar{u}_\varepsilon \rightarrow u^* \quad \text{in} \quad W_0^{1,\alpha}(\Omega). \quad (3.12)$$

Next, we write (3.11) as

$$\begin{aligned} \int_{\Omega} \varphi \sigma_\varepsilon \cdot (\nabla u_\varepsilon - \nabla \bar{u}_\varepsilon) &+ \int_{\Omega} \varphi \sigma_\varepsilon \cdot \nabla \bar{u}_\varepsilon - \int_{\Omega} \varphi \sigma_\varepsilon \cdot \nabla w_\varepsilon \\ &- \int_{\Omega} \varphi a_\varepsilon(x, \nabla w_\varepsilon) \cdot \nabla (u_\varepsilon - w_\varepsilon) \\ &:= I_1 + I_2 + I_3 + I_4. \end{aligned} \quad (3.13)$$

Since  $0 \leq \varphi \leq 1$  on  $\Omega$ , and  $K_\varepsilon$  is convex, then the function  $v = \varphi \bar{u}_\varepsilon + (1-\varphi)u_\varepsilon$  can be used as a test function in (1.8), which gives

$$\int_{\Omega} \sigma_\varepsilon \cdot \nabla (\varphi (\bar{u}_\varepsilon - u_\varepsilon)) \geq \int_{\Omega} f \varphi (\bar{u}_\varepsilon - u_\varepsilon) \quad (3.14)$$

and so

$$\begin{aligned} I_1 &= \int_{\Omega} \sigma_\varepsilon \cdot \nabla (\varphi (u_\varepsilon - \bar{u}_\varepsilon)) - \int_{\Omega} (u_\varepsilon - \bar{u}_\varepsilon) \sigma_\varepsilon \cdot \nabla \varphi \\ &\leq \int_{\Omega} f \varphi (u_\varepsilon - \bar{u}_\varepsilon) - \int_{\Omega} (u_\varepsilon - \bar{u}_\varepsilon) \sigma_\varepsilon \cdot \nabla \varphi. \end{aligned}$$

Since  $u_\varepsilon$  and  $\bar{u}_\varepsilon$  converge to  $u^*$  weakly in  $W_0^{1,\alpha}(\Omega)$  (and strongly in  $L^\alpha(\Omega)$ ), we obtain

$$\limsup_{\varepsilon \rightarrow 0} I_1 \leq 0. \quad (3.15)$$

As we know from (3.12),  $\bar{u}_\varepsilon \rightarrow u^*$  in  $W_0^{1,\alpha}(\Omega)$ , which gives

$$\lim_{\varepsilon \rightarrow 0} I_2 = \int_{\Omega} \varphi \sigma^* \cdot \nabla u^*. \quad (3.16)$$

Note that

$$I_3 = - \int_{\Omega} \sigma_\varepsilon \cdot \nabla (\varphi w_\varepsilon) + \int_{\Omega} w_\varepsilon \sigma_\varepsilon \cdot \nabla \varphi.$$

From (3.7) and (3.12), we pass to the limit in the first term of  $I_3$ . Using (3.3) and (3.12), we pass to the limit also in the second term of  $I_3$ , arriving at

$$\lim_{\varepsilon \rightarrow 0} I_3 = - \int_{\Omega} \varphi \sigma^* \nabla w_0. \quad (3.17)$$

Observe that

$$I_4 = - \int_{\Omega} a_\varepsilon(x, \nabla w_\varepsilon) \cdot \nabla (\varphi (u_\varepsilon - w_\varepsilon)) + \int_{\Omega} (u_\varepsilon - w_\varepsilon) a_\varepsilon(x, \nabla w_\varepsilon) \cdot \nabla \varphi,$$

and recalling (3.2) and (3.9) and passing to the limit we obtain

$$\lim_{\varepsilon \rightarrow 0} I_4 = - \int_{\Omega} \varphi a_0(\nabla w_0) \cdot \nabla (u^* - w_0). \quad (3.18)$$



Combining (3.13), (3.15)-(3.18), one has

$$\int_{\Omega} \varphi(\sigma^* - a_0(\nabla w_0)) \cdot \nabla(u^* - w_0) \geq 0 \quad \text{for } w_0 \in \mathcal{D}(\Omega). \quad (3.19)$$

By density, (3.19) is true also for any  $w_0$  in  $W_0^{1,\alpha}(\Omega)$ . Consider  $w_0 = u^* + t\varphi$ , with  $t \geq 0$  and  $\varphi \in W_0^{1,\alpha}(\Omega)$ . Letting  $t \rightarrow 0$  and using Minty's trick as in [5, page 94] (see also [15]), we conclude

$$\sigma^* = a_0(\nabla u^*). \quad (3.20)$$

**Step 4** (*Lower semicontinuity of the energy*). From (3.11) and (3.13) one has

$$\begin{aligned} \int_{\Omega} \varphi \sigma_{\varepsilon} \cdot \nabla u_{\varepsilon} &\geq \int_{\Omega} \varphi \sigma_{\varepsilon} \cdot \nabla w_{\varepsilon} + \int_{\Omega} \varphi a_{\varepsilon}(x, \nabla w_{\varepsilon}) \cdot \nabla(u_{\varepsilon} - w_{\varepsilon}) \\ &= -I_3 - I_4. \end{aligned}$$

From (3.17), (3.18) and (3.20) for any  $w_0 \in \mathcal{D}(\Omega)$  we have

$$\begin{aligned} &\liminf_{\varepsilon \rightarrow 0} \int_{\Omega} \varphi \sigma_{\varepsilon} \cdot \nabla u_{\varepsilon} \\ &\geq \int_{\Omega} \varphi a_0(\nabla u^*) \cdot \nabla w_0 + \int_{\Omega} \varphi a_0(\nabla w_0) \cdot \nabla(u^* - w_0). \end{aligned} \quad (3.21)$$

Letting  $w_0$  go to  $u^*$  in  $W_0^{1,\alpha}(\Omega)$ , one gets from (3.21)

$$\liminf_{\varepsilon \rightarrow 0} \int_{\Omega} \varphi \sigma_{\varepsilon} \cdot \nabla u_{\varepsilon} \geq \int_{\Omega} \varphi a_0(\nabla u^*) \cdot \nabla u^*, \quad (3.22)$$

$\forall \varphi \in \mathcal{D}(\Omega)$  such that  $0 \leq \varphi \leq 1$ .

**Step 5.** Finally, we claim that  $u^*$  is the unique solution  $u_0$  of (1.9).

Let  $v_0 \in K_0$  and since  $K_{\varepsilon} \rightarrow K_0$  in the Mosco sense, then there is a sequence  $\bar{v}_{\varepsilon} \in K_{\varepsilon}$  such that  $\bar{v}_{\varepsilon} \rightarrow v_0$  in  $W_0^{1,\alpha}(\Omega)$ . Using  $\bar{v}_{\varepsilon}$  as a test function in (1.8) for  $\varphi \in \mathcal{D}(\Omega)$ ,  $0 \leq \varphi \leq 1$ , one gets

$$\int_{\Omega} \sigma_{\varepsilon} \cdot \nabla \bar{v}_{\varepsilon} - \int_{\Omega} f(\bar{v}_{\varepsilon} - u_{\varepsilon}) \geq \int_{\Omega} \sigma_{\varepsilon} \cdot \nabla u_{\varepsilon} \geq \int_{\Omega} \varphi(\sigma_{\varepsilon} \cdot \nabla u_{\varepsilon}). \quad (3.23)$$

Recalling (3.22) and passing to the limit in  $\varepsilon$  in (3.23), we obtain

$$\int_{\Omega} a_0(\nabla u^*) \cdot \nabla v_0 - \int_{\Omega} f(v_0 - u^*) \geq \int_{\Omega} \varphi a_0(\nabla u^*) \cdot \nabla u^*.$$

Letting  $\varphi \rightarrow 1$  in the last inequality, one gets

$$\int_{\Omega} a_0(\nabla u^*) \cdot \nabla(v_0 - u^*) - \int_{\Omega} f(v_0 - u^*) \geq 0, \quad \forall v_0 \in K_0.$$

The latter, combined with (3.6), allow us to conclude that  $u^*$  coincides with the unique solution  $u_0$  of (1.9) and the whole sequence  $u_{\varepsilon} \rightharpoonup u_0$  in  $W_0^{1,\alpha}(\Omega)$ .  $\square$

**Remark 3.1.** *One can also show the convergence of the energies. More precisely,*

$$\int_{\Omega} a_{\varepsilon}(x, \nabla u_{\varepsilon}) \cdot \nabla u_{\varepsilon} dx \rightarrow \int_{\Omega} a_0(\nabla u_0) \cdot \nabla u_0 dx. \quad (3.24)$$

*Proof.* For any  $\varphi \in \mathcal{D}(\Omega)$  such that  $0 \leq \varphi \leq 1$  from (3.14) we have

$$\int_{\Omega} \varphi \sigma_{\varepsilon} \cdot \nabla u_{\varepsilon} \leq \int_{\Omega} \sigma_{\varepsilon} \cdot \nabla(\varphi \bar{u}_{\varepsilon}) - \int_{\Omega} u_{\varepsilon} \sigma_{\varepsilon} \cdot \nabla \varphi - \int_{\Omega} f \varphi (\bar{u}_{\varepsilon} - u_{\varepsilon}),$$

which gives

$$\limsup_{\varepsilon \rightarrow 0} \int_{\Omega} \varphi \sigma_{\varepsilon} \cdot \nabla u_{\varepsilon} \leq \int_{\Omega} a_0(\nabla u_0) \cdot \nabla u_0. \quad (3.25)$$

The latter, combined with (3.22), implies

$$\sigma_{\varepsilon} \cdot \nabla u_{\varepsilon} \rightarrow a_0(\nabla u_0) \cdot \nabla u_0 \quad \text{in } \mathcal{D}'(\Omega).$$

Since  $K_{\varepsilon} \rightarrow K_0$  in the Mosco sense, then taking  $v_0 = u_0$  in (3.23), we get

$$\begin{aligned} \int_{\Omega} a_0(\nabla u_0) \cdot \nabla u_0 &\geq \limsup_{\varepsilon \rightarrow 0} \int_{\Omega} \sigma_{\varepsilon} \cdot \nabla u_{\varepsilon} \\ &\geq \liminf_{\varepsilon \rightarrow 0} \int_{\Omega} \sigma_{\varepsilon} \cdot \nabla u_{\varepsilon} \\ &\geq \int_{\Omega} \varphi a_0(\nabla u_0) \cdot \nabla u_0, \end{aligned}$$

and letting  $\varphi \rightarrow 1$ , we obtain (3.24).  $\square$

**Remark 3.2.** *If in (1.8) we have  $f_{\varepsilon}$  instead of  $f$  and  $f_{\varepsilon} \rightharpoonup f$  in  $L^s(\Omega)$ , then the conclusion of the Theorem 3.1 still holds.*

**Remark 3.3.** *Since there are Lewy-Stampacchia inequalities also for the two obstacles problem (see [19]), the Theorem 3.1 can be extended for two obstacles problems with similar assumptions.*

#### 4. CONVERGENCE OF THE COINCIDENCE SETS

In this section, using the Lewy-Stampacchia inequalities, we prove a stability result for the coincidence sets as it was done, for example, in Theorem 6:6.1 in [18].

**Theorem 4.1.** *Let the conditions of Theorem 3.1 hold. If, as  $\varepsilon \rightarrow 0$ ,*

$$u_{\varepsilon} - \psi_{\varepsilon} \rightarrow u_0 - \psi_0 \quad \text{in } L^1(\Omega), \quad (4.1)$$

$$(A_{\varepsilon} \psi_{\varepsilon} - f)^+ \rightarrow (A_0 \psi_0 - f)^+ \quad \text{in } L^1(\Omega), \quad (4.2)$$

$$A_{\varepsilon} u_{\varepsilon} \rightarrow A_0 u_0 \quad \text{in } \mathcal{D}'(\Omega), \quad (4.3)$$

$$\int_S d(A_0 \psi_0 - f) \neq 0, \quad \forall S \subset \Omega \quad \text{such that } |S| > 0, \quad (4.4)$$

and

$$A_0 u_0 - f = (A_0 \psi_0 - f) \chi_0 \quad \text{a.e. in } \Omega, \quad (4.5)$$

where  $\chi_0$  is the characteristic function of the set  $I_0 := \{u_0 = \psi_0\}$ , then the coincidence sets  $I_\varepsilon := \{u_\varepsilon = \psi_\varepsilon\}$  converge in measure, i.e.,

$$\chi_\varepsilon \rightarrow \chi_0 \text{ in } L^p(\Omega), \forall p \in [1, \infty),$$

where  $\chi_\varepsilon$  is the characteristic function of  $I_\varepsilon$ .

*Proof.* From the Lewy-Stampacchia inequalities we have

$$f \leq A_\varepsilon u_\varepsilon \leq f + (A_\varepsilon \psi_\varepsilon - f)^+ \text{ a.e. in } \Omega.$$

Hence, there exists a function  $q_\varepsilon \in L^\infty(\Omega)$ , such that,

$$A_\varepsilon u_\varepsilon - f = q_\varepsilon (A_\varepsilon \psi_\varepsilon - f)^+ \text{ a.e. in } \Omega, \quad (4.6)$$

and

$$0 \leq q_\varepsilon \leq \chi_\varepsilon \leq 1 \text{ a.e. in } \Omega. \quad (4.7)$$

Then for a subsequence (still denoted by  $\varepsilon$ ), one has

$$q_\varepsilon \rightarrow q \text{ and } \chi_\varepsilon \rightarrow \chi_* \text{ in } L^\infty(\Omega) - \text{weak}^* \quad (4.8)$$

for functions  $q, \chi_* \in L^\infty(\Omega)$ . The inequalities (4.7) imply

$$0 \leq q \leq \chi_* \leq 1 \text{ a.e. in } \Omega. \quad (4.9)$$

Using (4.2), (4.3) and (4.8), we pass to the limit, as  $\varepsilon \rightarrow 0$ , in (4.6) and obtain

$$A_0 u_0 - f = q (A_0 \psi_0 - f)^+ \text{ a.e. in } \Omega.$$

The latter, combined with (4.5) provides

$$q (A_0 \psi_0 - f)^+ = (A_0 \psi_0 - f) \chi_0 \text{ a.e. in } \Omega. \quad (4.10)$$

Note that in the region  $\{A_0 \psi_0 > f\}$ , (4.10) and (4.4) imply that  $q = \chi_0$ , while in  $\{A_0 \psi_0 \leq f\}$ ,  $\chi_0 = 0$ . Therefore,  $q \geq \chi_0$  a.e. in  $\Omega$ . Consequently, from (4.9) we get

$$\chi_0 \leq \chi_* \text{ a.e. in } \Omega.$$

On the other hand, from (4.1) and (4.8) one has

$$0 = \int_{\Omega} \chi_\varepsilon (u_\varepsilon - \psi_\varepsilon) \rightarrow \int_{\Omega} \chi_* (u_0 - \psi_0) = 0,$$

thus  $\chi_* (u_0 - \psi_0) = 0$  a.e. in  $\Omega$ . Consequently, if  $u_0 > \psi_0$ , then  $\chi_* = 0$ , and since  $0 \leq \chi_* \leq 1$ , one obtains

$$\chi_0 \geq \chi_* \text{ a.e. in } \Omega.$$

Therefore,  $\chi_0 = \chi_*$ , and the whole sequence  $\chi_\varepsilon$  converges to  $\chi_0$  as  $\varepsilon \rightarrow 0$ , first weakly, and since they are characteristic functions, also strongly in any  $L^p(\Omega)$ , for any  $p \in [1, \infty)$ .  $\square$

**Remark 4.1.** *If  $\psi_0 = 0$  and the right hand side is regular enough, the condition (4.5) holds automatically, since in this particular case one has porosity of the free boundary from [9] (hence, the free boundary has Lebesgue measure zero), which provides (4.5).*

**Remark 4.2.** *The assumption (4.4) is a weaker version of the condition*

$$A_0\psi_0 - f \neq 0 \text{ a.e. in } \Omega, \text{ when } A_0\psi_0 \in L^1(\Omega).$$

**Theorem 4.2.** *Let the conditions of Theorem 3.1 and also  $s > n/2$ . If  $\psi_\varepsilon \rightarrow \psi_0$ , uniformly,  $\psi_0|_{\partial\Omega} < 0$  and*

$$\overline{\text{int}\{u_0 = \psi_0\}} = \{u_0 = \psi_0\} = I_0,$$

*then the coincidence sets  $I_\varepsilon := \{u_\varepsilon = \psi_\varepsilon\}$  converge in the Hausdorff distance to  $I_0$ .*

*Proof.* Using [13, Theorem 3.2], we obtain the uniform Hölder continuity of solutions. The uniform Hölder continuity of the obstacles then implies, as  $\varepsilon \rightarrow 0$ , the convergence  $u_\varepsilon \rightarrow u_0$ , uniformly in compact subsets of  $\Omega$ . This, in turn, provides the convergence of the coincidence sets in Hausdorff distance as in [8] and [18, Theorem 6:6.5].  $\square$

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